15-300mm F4

Thermal Imaging System Specification

15-300mm F4 Thermal Imaging System Specification is an advanced MWIR cooled thermal imaging used for long-distance detection. The highly sensitive MWIR cooled core with 640x512 resolution can produce very clear image with very high resolution; the $15\text{mm} \sim 300\text{mm}$ continuous zoom infrared lens used in the product can effectively distinguish targets such as people, vehicles and ships in long distance.



Figure 1 Thermal imaging image

1 Technical Specification

1.1 Detector

Detector MCT 640 ×512

Spectral range 3.7 ~4.8μm

Pixel pitch 15μm

Cooling method Stirling Refrigerator

1.2 Lens

Focal length $15 \text{ mm} \sim 300 \text{ mm}$ continuous zoom

F 4

1.3 Performance

FOV range $1.83^{\circ}(H) \times 1.46^{\circ} (V) \text{ to } 36.5^{\circ}(H) \times 29.2^{\circ} (V)$

Cooling time ≤8 minutes in normal temperature

Video Output standard PAL format analog video signal

Frame Frequency 50Hz

NETD ≤25mk@25°C

Power source DC 24 ~32 V, with power reverse polarity

protection

Power consumption $\leq 15 \text{W} @ 25 ^{\circ} \text{C}$, steady state

 $\leq 30 \text{W} @ 25 ^{\circ}\text{C}$, start-up peak

Operation Temperature $-30^{\circ}\text{C} \sim 55^{\circ}\text{C}$

Storage Temperature $-40^{\circ}\text{C} \sim 70^{\circ}\text{C}$

1.4 Command and Control

Control communication RS232

Correction manual correction/background correction

Polarity control white hot/black hot switch

Electronic Zoom ×2/×4 electronic zoom

Image enhancement Yes

Cross display Yes

Image turning Horizontal/vertical

2 Physical Parameters

Weight ≤2200g

Sizes see below

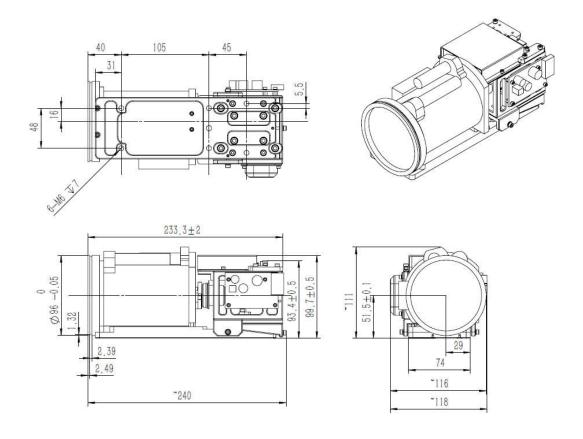


Figure 2. Mechanical size illustration

3 Core Electrical Interface Definition

Table 1. Connector (HARWIN:M80-5401605) pin definitions

| Pin Number | Definitions |
|------------|----------------|
| 1,9 | Power +, input |
| 2,10 | Power -, input |
| 3 | Video + output |
| 11 | Video GND |
| 4 | RS422_A |
| 12 | RS422_B |
| 5 | RS422_Z |
| 13 | RS422_Y |
| 6 | RS232_RX |
| 14 | RS232_TX |
| 7 | GND |
| 15 | GND |
| 8 | SER_LVDS_OUT- |
| 16 | SER_LVDS_OUT+ |

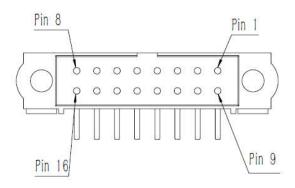


Figure 3. M80-5401605 pin sequence diagram

4 Communication protocol

4.1 Electrical Interface Description for Communication

Channel

Communication between the thermal infrared imager and the host is achieved via an RS232 asynchronous serial communication interface, whose serial port setting is as follows:

Baud rate: 19200 bps

Start bits 1 bit

Stop bits: 1 bit

Verification: None

Data bits: 8 bit

The parameters listed above may be different in practice, subject to requirement of the client.

4.2 Software Interface Description for Communication

Protocol

a) The host controls the certain action of the thermal infrared imager by sending commands to the thermal infrared imager through the serial port; communication command is sent in given packet format; if the interval between characters of the packet sent from the host to the thermal infrared imager is over 10ms, the imaging system may decline to implement the command.

b) Packet Protocol

Packet protocol is defined in Figure 4: Packet Protocol.

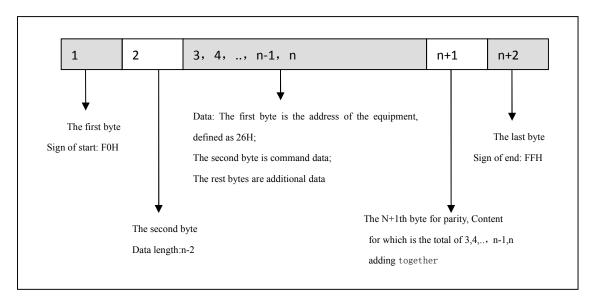


Figure 4 Packet Protocol

Table2. Communication data packet protocol explanation

| Data packet protocol | Explanation |
|----------------------------------|---|
| * | |
| Start sign | 1 byte, hex value FOH |
| Data length | 1 byte, X |
| Data | Data of X bytes |
| Checksum | low 8 bytes for the sum of X bytes |
| End sign | 1 byte, hex value FFH |
| Data Link Escape Character | In the packet, if "FOH" emerges in data other than the signs of start and end, i.e. data between the second and N+1th, it should be changed to "F5H 00H"; "FFH" should be changed to "F5H 0FH"; "F5H" should be changed to "F5H 05H". |

| Note data | Data length of the packet shall be determined by the number of | | | |
|-----------|--|--|--|--|
| | effective data, and there is no need for bytes of the escape | | | |
| length | character to be added in. | | | |

4.3 Communication Protocol Control Commands List

Communication protocol control commands list—pool of commands that can be sent from the host. See Table 3.

Table3 Communication Protocol Control Commands List

| Name of Command | Equipment Address | Function Code | Additional Data | Notes |
|--------------------------|----------------------|---------------|--|--|
| Status Inquiry | 26H | 00H | | With feedback |
| background correction | 26H | 02H | | |
| manual correction | 26H | 03H | | |
| Crosshair display | 26Н | 04Н | 1 byte. 00H is for crosshair hiding; 0FH is for crosshair showing | |
| Polarity setting | 26Н | 05Н | 1 byte. 00H is for white hot; 0FH is for black hot | |
| Gamma adjustment | 26Н | 06Н | 1 byte, 1~23, default value is 8. | |
| Auto correction setting | 26Н | 07Н | 1 byte. 00H is for off; 0FH is for on | Automatic manual correction, default setting off |
| Electronic zoom setting | 26Н | 08H | 1 byte. 00H is for off; 0FH is for on | |
| Video gain setting | 26Н | 09Н | 1 byte. 0~255. Default value is 128 | |
| Video brightness setting | 26Н | 0AH | 1 byte. 0~255. Default value is 128 | |
| Crosshair X coordinate | 26Н | 0ВН | 2 bytes. 0~65535 from low to high | |
| Crosshair Y coordinate | 26Н | 0СН | 2 bytes. 0~65535 from low to high | |
| Image enhancement | 26Н | 0ЕН | 1 byte. 00H is for off; 0FH is for on | |
| DDE setting | 26H | 77H | 1 byte, 0~255. | |

| | | | 1 | |
|----------------------|------|--------|----------------------|-----------------|
| Focus position value | 26H | 18H | 3bytes, first byte | |
| setting | | | is"12H" | |
| | | | 2~3byte:0~65535 from | |
| | | | low to high | |
| Zoom position value | 26H | 18H | 3bytes, first byte | |
| setting | | | is"22H" | |
| | | | 2~3byte:0~65535 from | |
| | | | low to high | |
| Inquire Focus & zoom | 26H | 1DH | 1byte,00H | |
| position value | | | | |
| Inquire max and min | 26H | 1DH | 1byte,20H | |
| values of Focus & | | | | |
| zoom position | | | | |
| Read accumulated | 26H | 1DH | 10H | |
| working time | 20H | IDH | | |
| | | | 3bytes: | Doing |
| | | | 1byte:64H | automatic blind |
| | | | 2byte:51H | processing |
| Automatic blind | 26H | 57H | 3byte:62H | requires the |
| element processing | 2011 | 3/П | | thermal imager |
| | | | | to face the |
| | | | | uniform |
| | | | | background. |
| | | | | Restore the |
| | | | | default setting |
| System reset | 26Н | 80H | | for parameters |
| | | | | of the thermal |
| | | | | imager |
| | | 1 1:00 | 1 | |

The commands listed above may be different in practice, subject to requirement of the client. The set ID is 26H, but it can be changed according to application environment.

4.4 Communication Protocol Feedback Commands List

Communication protocol feedback commands list – pool of the thermal infrared imager feedback commands.

Instead of actively sending data, the thermal infrared imager only responds when it receives "status inquiry" command. Its responding packet conforms to "communication packet protocol".

Table4. Communication Protocol feedback commands list

| Responding | Equipment | Function | Additional Data | |
|----------------|-----------|----------|--|--|
| packet | address | Code | | |
| Status inquiry | 26Н | 00H | The first byte: | |
| | | | B0: Crosshair display, 0 is off, 1 is on; | |
| | | | B1: Polarity indication, 0 is white hot, 1 is black | |
| | | | hot; | |
| | | | B2: Auto correction setting, 0 is off, 1 is on; | |
| | | | B3: electronic zoom setting, 0 is off, 1 is on; | |
| | | | B5: Image enhance setting, 0 is off, 1 is on; | |
| | | | The rest are reserved, setting as 0. | |
| | | | The second byte: video gain. | |
| | | | The third byte: video brightness. | |
| | | | The fourth and fifth bytes: crosshair X coordinate, | |
| | | | from low to high. | |
| | | | The sixth and seventh bytes: crosshair Y coordinate, | |
| | | | from low to high. | |
| | | | The eighth byte: Gamma | |
| | | | From the ninth to the sixteenth bytes: reserved. | |
| Inquire Focus | 26Н | 1DH | The first byte:06H,cmd type | |
| & zoom | | | 2~3byte: temperature of core | |
| position | | | 4~5byte: zoom position value | |
| value | | | 6~7byte: focus position value | |
| | | | | |
| Inquire max | 26Н | 1DH | The first byte:28H,cmd type | |
| and min | | | 2~3byte: Min value of focus position | |
| value of | | | 4~5byte: Max value of focus position | |
| Focus & | | | 6~7byte: Min value of zoom position | |
| zoom | | | 8~9byte: Max value of zoom position | |

| position | | | |
|--------------|-----|-----|--|
| Inqure | 26Н | 1DH | The first byte:16H |
| working time | | | 2~5byte: working time, from low to high, |
| | | | 1LSB=1s |
| | | | 6~7byte: Boot times, from low to high, |
| | | | The rest are reserved |

The commands listed above may be different in practice, subject to requirement of the client. The set ID is 26H, but it can be changed according to application environment.

5 Digital video interfaces

LVDS transmission chip MAX9257 (use MAX9258 to receive). Definitions are in Table 5.

Table 5. LVDS signal list

| MAX9257 | Digital image definition |
|---------|---|
| Din0 | Pxl_D0: image data, the 0th (the lowest) |
| Din1 | Pxl_D1: image data, the 1th |
| Din2 | Pxl_D2: image data, the 2nd |
| Din3 | Pxl_D3: image data, the 3rd |
| Din4 | Pxl_D4: image data, the 4th |
| Din5 | Pxl_D5: image data, the 5th |
| Din6 | Pxl_D6: image data, the 6th |
| Din7 | Pxl_D7: image data, the 7th |
| Din8 | Pxl_D8: image data, the 8th |
| Din9 | Pxl_D9: image data, the 9th |
| Din10 | Pxl_D10: image data, the 10th |
| Din11 | Pxl_D11: image data, the 11th |
| Din12 | Pxl_D12: image data, the 12th |
| Din13 | Pxl_D13: image data, the 13th (the highest) |

| HSYNC | HS: line synchronized and high efficient |
|--------|---|
| VSYNC | FS: field synchronized and high efficient |
| PCLK | Pxl_Clk: pixel clock |
| Others | Reserved |

Data time sequence which is transmitted to MAX9257 transmission chip is showed in the following figure.

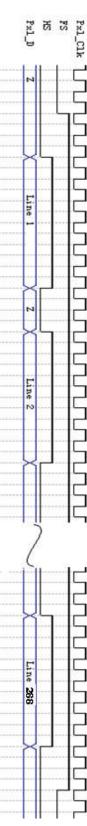


Figure 5. Data time sequence transmitted to MAX9257 transmission chip